

О представлении группы виртуальных кос, связанном с кластерными алгебрами

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K. Hikami, R. Inoue, Braids, complex volume and cluster algebra,
Algebraic and Geometric Topology 15 (2015), 2175–2194.

A cluster seed (\mathbf{x}, \mathbf{B}) is a pair of

- a cluster variable $\mathbf{x} = (x_1, \dots, x_N)$: an N -tuple of algebraically independent variables,
- an exchange matrix $\mathbf{B} = (b_{ij})$: an $N \times N$ skew symmetric integer matrix.

For each $k = 1, \dots, N$, we define the mutation μ_k of (\mathbf{x}, \mathbf{B}) by

$$\mu_k(\mathbf{x}, \mathbf{B}) = (\tilde{\mathbf{x}}, \tilde{\mathbf{B}}),$$

where

- $\tilde{\mathbf{x}} = (\tilde{x}_1, \dots, \tilde{x}_N)$ is

$$\tilde{x}_i = \begin{cases} x_i, & \text{for } i \neq k, \\ \frac{1}{x_k} \left(\prod_{j:b_{jk}>0} x_j^{b_{jk}} + \prod_{j:b_{jk}<0} x_j^{-b_{jk}} \right), & \text{for } i = k, \end{cases}$$

- $\tilde{\mathbf{B}} = (\tilde{b}_{ij})$ is

$$\tilde{b}_{ij} = \begin{cases} -b_{ij}, & \text{for } i = k \text{ or } j = k, \\ b_{ij} + \frac{|b_{ik}| b_{kj} + b_{ik} |b_{kj}|}{2}, & \text{otherwise.} \end{cases}$$

In terms of the cluster variable \boldsymbol{x} , we introduce the y -variable, $\boldsymbol{y} = (y_1, \dots, y_N)$, defined by

$$y_j = \prod_k x_k^{b_{kj}}.$$

The mutation μ_k induces a mutation of a pair (\mathbf{y}, \mathbf{B}) :

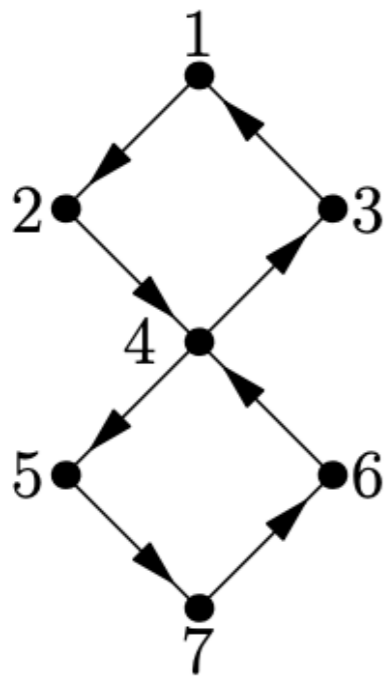
$$\mu_k(\mathbf{y}, \mathbf{B}) = (\tilde{\mathbf{y}}, \tilde{\mathbf{B}}),$$

where $\tilde{\mathbf{B}}$ is (2.3), and $\tilde{\mathbf{y}} = (\tilde{y}_1, \dots, \tilde{y}_N)$ with $\tilde{y}_j = \prod_k \tilde{x}_k^{\tilde{b}_{kj}}$ is given by

$$\tilde{y}_i = \begin{cases} y_k^{-1}, & \text{for } i = k, \\ y_i (1 + y_k^{-1})^{-b_{ki}}, & \text{for } i \neq k, b_{ki} \geq 0, \\ y_i (1 + y_k)^{-b_{ki}}, & \text{for } i \neq k, b_{ki} \leq 0. \end{cases}$$

7 variables

Consider case when we have 7 variables $\mathbf{x} = (x_1, x_2, x_3, x_4, x_5, x_6, x_7)$ and matrix \mathbf{B} is taken as an adjacency matrix of the oriented graph below.



$$R = s_{3,5} s_{2,5} s_{3,6} \mu_4 \mu_2 \mu_6 \mu_4.$$

$$R^{-1} = s_{3,6} s_{2,5} s_{3,5} \mu_4 \mu_5 \mu_3 \mu_4.$$

The permutations are included in the R-operator so that the exchange matrix \mathbf{B} is invariant under R.

Action of R on x-variables

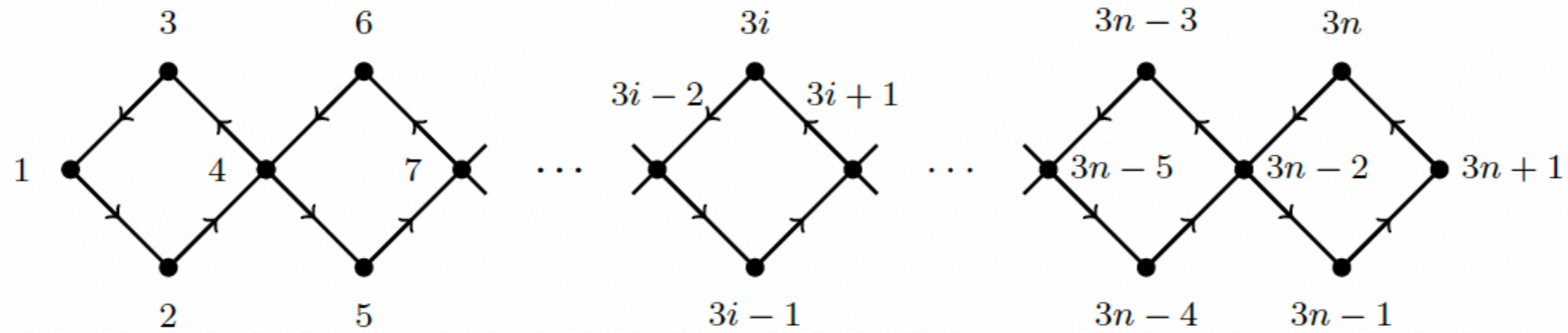
$$R(\mathbf{x}) = \begin{pmatrix} x_1 \\ x_5 \\ \frac{x_1 x_3 x_5 + x_3 x_4 x_5 + x_1 x_2 x_6}{x_2 x_4} \\ \frac{x_1 x_3 x_4 x_5 + x_3 x_4^2 x_5 + x_1 x_3 x_5 x_7 + x_3 x_4 x_5 x_7 + x_1 x_2 x_6 x_7}{x_2 x_4 x_6} \\ \frac{x_3 x_4 x_5 + x_3 x_5 x_7 + x_2 x_6 x_7}{x_4 x_6} \\ x_3 \\ x_7 \end{pmatrix}^T,$$

$$R^{-1}(\mathbf{x}) = \begin{pmatrix} x_1 \\ \frac{x_1 x_3 x_5 + x_1 x_2 x_6 + x_2 x_4 x_6}{x_3 x_4} \\ x_6 \\ \frac{x_1 x_2 x_4 x_6 + x_2 x_4^2 x_6 + x_1 x_3 x_5 x_7 + x_1 x_2 x_6 x_7 + x_2 x_4 x_6 x_7}{x_3 x_4 x_5} \\ x_2 \\ \frac{x_2 x_4 x_6 + x_3 x_5 x_7 + x_2 x_6 x_7}{x_4 x_5} \\ x_7 \end{pmatrix}^T.$$

Action of R on y-variables

$$\mathbf{R}(\mathbf{y}) = \begin{pmatrix} \frac{y_1 (1 + y_2 + y_2 y_4)}{y_2 y_4 y_5 y_6} \\ \frac{1 + y_2 + y_6 + y_2 y_6 + y_2 y_4 y_6}{1 + y_2 + y_6 + y_2 y_6 + y_2 y_4 y_6} \\ \frac{y_2 y_4}{y_4} \\ \frac{(1 + y_2 + y_2 y_4) (1 + y_6 + y_4 y_6)}{1 + y_2 + y_6 + y_2 y_6 + y_2 y_4 y_6} \\ \frac{y_4 y_6}{y_2 y_3 y_4 y_6} \\ \frac{1 + y_2 + y_6 + y_2 y_6 + y_2 y_4 y_6}{(1 + y_6 + y_4 y_6) y_7} \end{pmatrix}^T, \quad \mathbf{R}^{-1}(\mathbf{y}) = \begin{pmatrix} \frac{y_1 y_3 y_4}{1 + y_4 + y_3 y_4} \\ \frac{y_5}{1 + y_4 + y_3 y_4 + y_4 y_5 + y_3 y_4 y_5} \\ \frac{(1 + y_4 + y_3 y_4 + y_4 y_5 + y_3 y_4 y_5) y_6}{(1 + y_4 + y_3 y_4)(1 + y_4 + y_4 y_5)} \\ \frac{y_3 y_4 y_5}{y_2 (1 + y_4 + y_3 y_4 + y_4 y_5 + y_3 y_4 y_5)} \\ \frac{y_3}{1 + y_4 + y_3 y_4 + y_4 y_5 + y_3 y_4 y_5} \\ \frac{y_4 y_5 y_7}{1 + y_4 + y_4 y_5} \end{pmatrix}^T.$$

General case



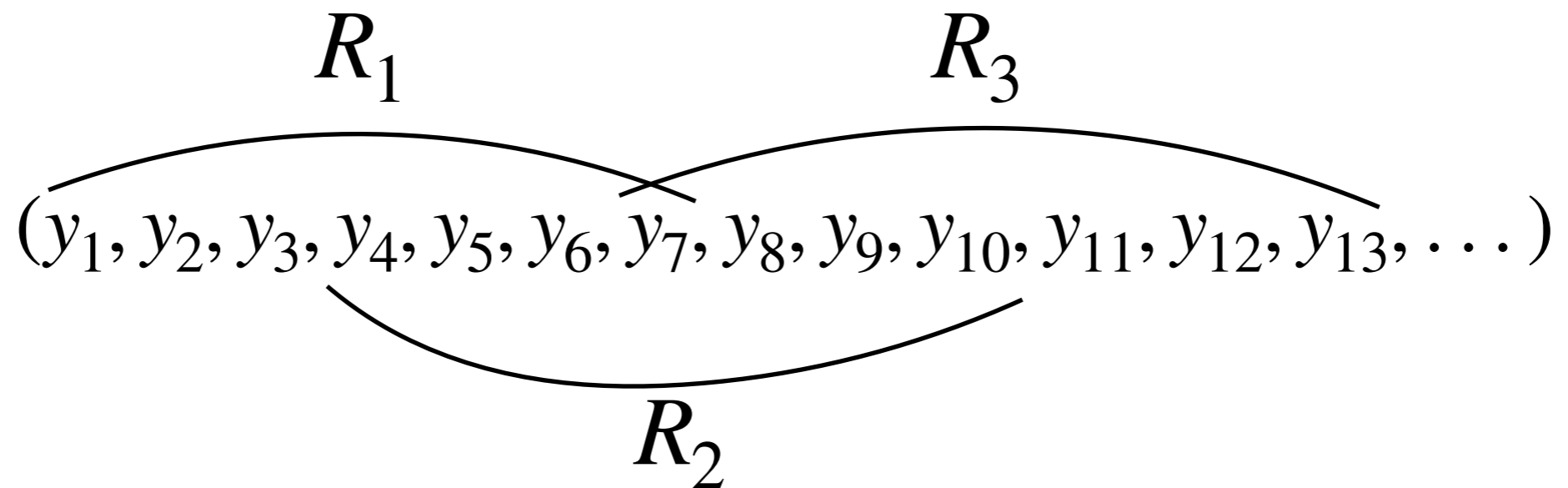
$$(x_1, x_2, x_3, x_4 \dots, x_{3n}, x_{3n+1})$$

$$(y_1, y_2, y_3, y_4 \dots, y_{3n}, y_{3n+1})$$

And \mathbf{B} is taken as an adjacency matrix of the oriented graph above.

R_i operators

With $3n + 1$ we have exactly $n - 1$ $R_i, i = 1, \dots, n - 1$, operators.



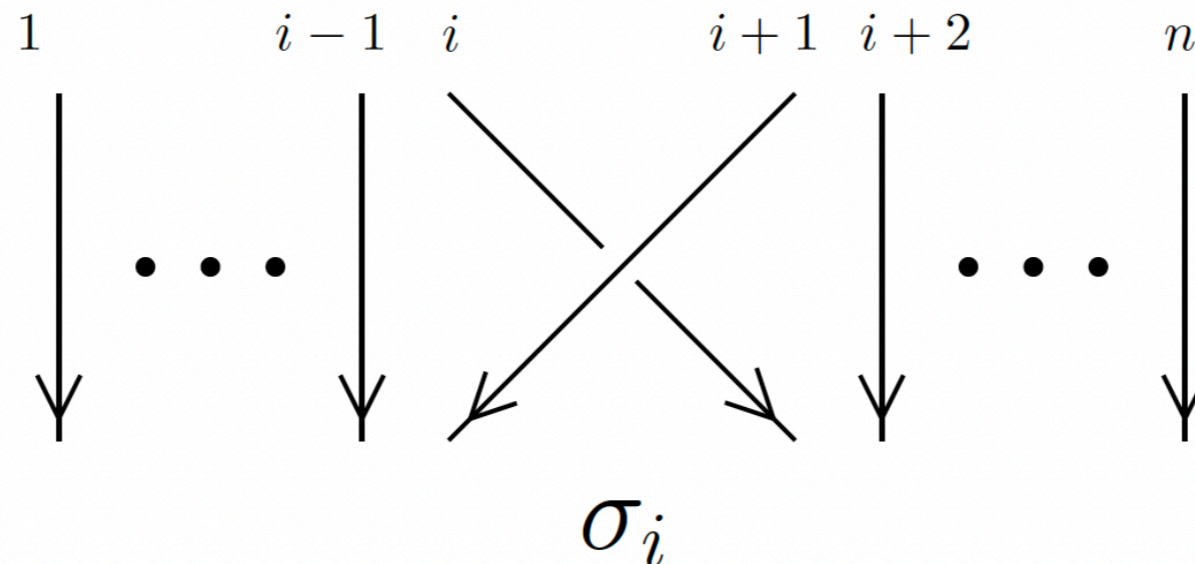
Operator R_i acts variables $y_{3i-2}, y_{3i-1}, \dots, y_{3i+4}$.

Braid group

For $n \geq 2$, the braid group B_n is defined as a group with generators $\sigma_1, \dots, \sigma_{n-1}$ and the following defining relations:

$$\begin{aligned}\sigma_i \sigma_j &= \sigma_j \sigma_i, & |i - j| \geq 2. \\ \sigma_i \sigma_{i+1} \sigma_i &= \sigma_{i+1} \sigma_i \sigma_{i+1}, & i = 1, 2, \dots, n - 2,\end{aligned}$$

The generators σ_i have the following geometric interpretation:

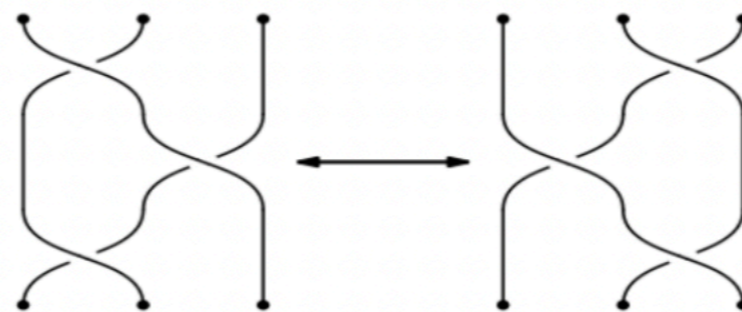
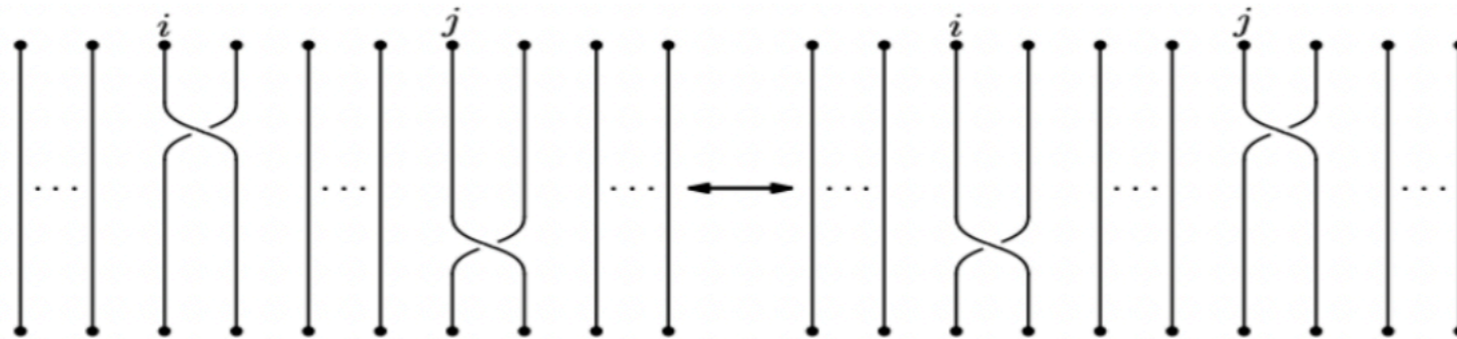


Braid group

$$\sigma_i \sigma_j = \sigma_j \sigma_i, \quad |i - j| \geq 2.$$

$$\sigma_i \sigma_{i+1} \sigma_i = \sigma_{i+1} \sigma_i \sigma_{i+1}, \quad i = 1, 2, \dots, n - 2,$$

The relations have the following geometric interpretation:



Braid group representation

Denote by \mathbf{W}_n the group generated by $R_i, i = 1, \dots, n - 1$, with composition as a group operation.

Define a map $F : B_n \rightarrow \mathbf{W}_n$ by setting

$$F(\sigma_i) = R_i.$$

Theorem (Hikami, Inoue, 2015) Map $F : B_n \rightarrow \mathbf{W}_n$ is a homomorphism.

So, the following relations are satisfied

$$\begin{aligned} R_i R_{i+1} R_i &= R_{i+1} R_i R_{i+1}, & i &= 1, \dots, n - 2, \\ R_i R_j &= R_j R_i, & |i - j| &> 2. \end{aligned}$$

Virtual braid group

The virtual braid group VB_n on n strings is the group with two families of generators, classical and virtual, denoted by $\sigma_1, \dots, \sigma_{n-1}$ and $\rho_1, \dots, \rho_{n-1}$, with the following defining relations:

Classical relations

$$\begin{aligned}\sigma_i \sigma_{i+1} \sigma_i &= \sigma_{i+1} \sigma_i \sigma_{i+1}, & i = 1, 2, \dots, n-2, \\ \sigma_i \sigma_j &= \sigma_j \sigma_i, & |i-j| \geq 2.\end{aligned}$$

Virtual relations

$$\begin{aligned}\rho_i \rho_{i+1} \rho_i &= \rho_{i+1} \rho_i \rho_{i+1}, & i = 1, 2, \dots, n-2, \\ \rho_i \rho_j &= \rho_j \rho_i, & |i-j| \geq 2, \\ \rho_i^2 &= 1, & i = 1, 2, \dots, n-1,\end{aligned}$$

Mixed relations

$$\begin{aligned}\sigma_i \rho_j &= \rho_j \sigma_i, & |i-j| \geq 2, \\ \rho_i \rho_{i+1} \sigma_i &= \sigma_{i+1} \rho_i \rho_{i+1}, & i = 1, 2, \dots, n-2.\end{aligned}$$

Forbidden relations

$$\begin{aligned}\rho_i \sigma_{i+1} \sigma_i &= \sigma_{i+1} \sigma_i \rho_{i+1}, \\ \rho_{i+1} \sigma_i \sigma_{i+1} &= \sigma_i \sigma_{i+1} \rho_i\end{aligned}$$

There is involutive non-trivial permutation T_i acting on $(y_{3i-2}, y_{3i-1}, y_{3i}, y_{3i+1}, y_{3i+2}, y_{3i+3}, y_{3i+4})$ for which the following mixed relations are satisfied

$$R_i R_{i+1} T_i = T_{i+1} R_i R_{i+1}, \quad i = 1, \dots, n - 2,$$

The idea now is not only to find suitable involution T_i , but also put some additional condition on y_i for which the relations above will be satisfied.

We also wanted the forbidden relations not to be fulfilled.

$$(y_1, y_2, y_3, y_4, y_5, y_6, y_7, y_8, y_9, y_{10}, y_{11}, y_{12}, y_{13})$$

The condition that works

$$T_i(y_{3i-2}, y_{3i-1}, y_{3i}, y_{3i+1}, y_{3i+2}, y_{3i+3}, y_{3i+4}) = (y_{3i+1}, y_{3i+2}, y_{3i+3}, y_{3i-2}, y_{3i-1}, y_{3i}, y_{3i+4})$$

The condition is that $y_1 = y_4 = y_7 = \dots y_{3n+1} = -1$.

Easy to this condition is stable under the action of R_i and T_i :

Let $\mathbf{y} = (-1, y_2, y_3, -1, y_5, y_6, -1, \dots)$, then $R_i(\mathbf{y})$ и $T_i(\mathbf{y})$ have -1 on 1st, 4th, 7th, ... places.

$$R_i R_{i+1} T_i = T_{i+1} R_i R_{i+1}, \quad i = 1, \dots, n-2,$$

The final operators

At the end we have vector $\mathbf{z} = (z_1, z_2, \dots, z_{2n})$ and two families of operators S_i and $T_i, i = 1, \dots, n - 1$.

$$S \begin{pmatrix} z_1 \\ z_2 \\ z_3 \\ z_4 \end{pmatrix}^T = \begin{pmatrix} -\frac{z_1 z_3 z_4}{1 + z_1 + z_4} \\ -\frac{z_1}{1 + z_1 + z_4} \\ -\frac{z_4}{1 + z_1 + z_4} \\ -\frac{z_1 z_2 z_4}{1 + z_1 + z_4} \end{pmatrix}^T, \quad S^{-1} \begin{pmatrix} z_1 \\ z_2 \\ z_3 \\ z_4 \end{pmatrix}^T = \begin{pmatrix} -\frac{z_3}{z_2 + z_3 + z_2 z_3} \\ -(z_2 + z_3 + z_2 z_3) z_4 \\ -z_1 (z_2 + z_3 + z_2 z_3) \\ -\frac{z_2}{z_2 + z_3 + z_2 z_3} \end{pmatrix}^T$$

$$T(z_1, z_2, z_3, z_4) = (z_3, z_4, z_1, z_2).$$

$$\begin{array}{c} S_1, T_1 \qquad S_3, T_3 \\ \underbrace{\hspace{10em}} \\ (z_1, z_2, z_3, z_4, z_5, z_6, z_7, z_8, \dots) \\ \underbrace{\hspace{10em}} \\ S_2, T_2 \end{array}$$

Virtual braid group representation

Denote by Θ_n the group generated by S_i и $T_i, i = 1, \dots, n - 1$, with composition as a group operation.

Define a map $F : VB_n \rightarrow \Theta_n$ by setting

$$F(\sigma_i) = S_i, \quad F(\rho_i) = T_i$$

Theorem Map $F : VB_n \rightarrow \Theta_n$ is a homomorphism.

So, the following relations are satisfied

- (1) $S_i S_{i+1} S_i = S_{i+1} S_i S_{i+1}$, where $i = 1, 2, \dots, n - 2$.
- (2) $S_i S_j = S_j S_i$, where $|i - j| \geq 2$.
- (3) $T_i T_{i+1} T_i = T_{i+1} T_i T_{i+1}$, where $i = 1, 2, \dots, n - 2$.
- (4) $T_i T_j = T_j T_i$, where $|i - j| \geq 2$.
- (5) $T_i^2 = 1$, where $i = 1, 2, \dots, n - 1$.
- (6) $T_i T_{i+1} S_i = S_{i+1} T_i T_{i+1}$, where $i = 1, 2, \dots, n - 2$.

Forbidden relations

Theorem The forbidden relations are not satisfied for S_i and T_i .

Examples

Example 1. Let $w_1 = \sigma_1 \rho_1 \sigma_1 \in VB_2$. The operator $F(w_1)$ ($= S_1 T_1 S_1$) acts on $(1,2,2,1)$ in the following way:

$$F(w_1)(1,2,2,1) = \left(-\frac{6}{5}, -\frac{5}{3}, -\frac{5}{3}, -\frac{6}{5} \right) \neq (1,2,2,1).$$

Therefore, the homomorphism F distinguishes w_1 from a trivial braid.

Example 2. It is known that a generalized Burau representation does not distinguish a braid $w_2 = (\sigma_1^2 \rho_1 \sigma_1^{-1} \rho_1 \sigma_1^{-1} \rho_1)^2 \in VB_2$ from a trivial braid. The operator $F(w_2)$ acts on $(1,2,2,1)$ in the following way:

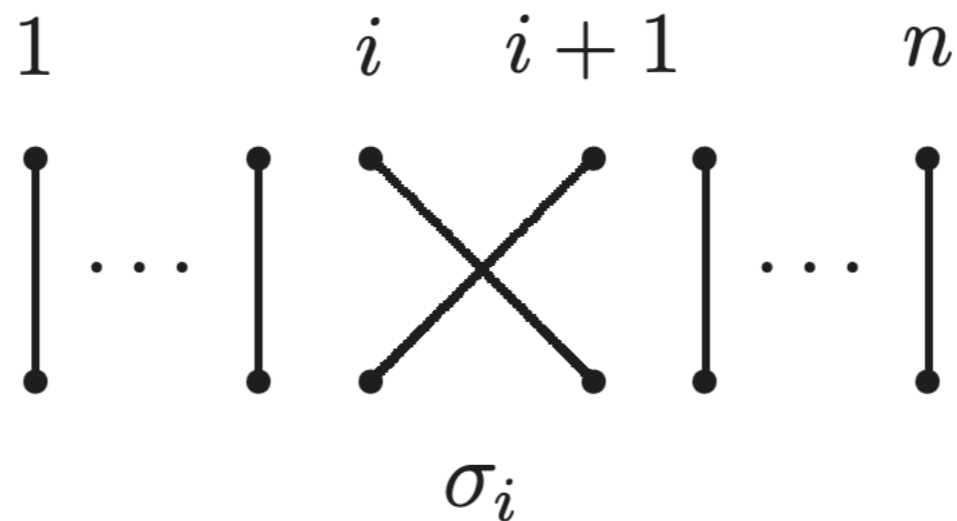
$$F(w_2)(1,2,2,1) = \left(-\frac{44}{19}, -\frac{19}{22}, -\frac{19}{22}, -\frac{44}{19} \right) \neq (1,2,2,1).$$

Therefore, the homomorphism F distinguishes w_2 from a trivial braid.

Flat virtual braid group

Flat virtual braid group FVB_n is a virtual braid group VB_n with additional relations

$$\sigma_i^2 = 1, \quad i = 1, 2, \dots, n - 1.$$



Adapting to flat braids

We noticed that if we consider vector of variables of the following form

$$\mathbf{z} = \left(z_1, \frac{1}{z_1}, z_3, \frac{1}{z_3}, \dots, z_{2n-1}, \frac{1}{z_{2n-1}} \right)$$

Then

1) $S_i(\mathbf{z}) = \left(\psi_1, \frac{1}{\psi_1}, \psi_3, \frac{1}{\psi_3}, \dots, \psi_{2n-1}, \frac{1}{\psi_{2n-1}} \right)$. And same for T_i .

2) $S_i^2(\mathbf{z}) = \mathbf{z}$

Flat virtual braid group representation

Consider $\mathbf{t} = (t_1, t_2, \dots, t_n)$ and define operators

$$R_i : \begin{cases} t_i \rightarrow -\frac{t_i t_{i+1}}{1 + t_{i+1} + t_i t_{i+1}}, \\ t_{i+1} \rightarrow -(1 + t_{i+1} + t_i t_{i+1}). \end{cases} \quad V_i : \begin{cases} t_i \rightarrow t_{i+1}, \\ t_{i+1} \rightarrow t_i. \end{cases}$$

Denote by Ψ_n the group generated by R_i и $V_i, i = 1, \dots, n - 1$, with composition as a group operation.

Define a map $F_{FVB} : FVB_n \rightarrow \Psi_n$ by setting

$$F(\sigma_i) = R_i, \quad F(\rho_i) = V_i$$

Theorem Map $F_{FVB} : FVB_n \rightarrow \Psi_n$ is a homomorphism.

Example

Example 3. Let $w_3 = \sigma_2 \rho_1 \sigma_1 \rho_2 \in FVB_3$. The operator $F_{FVB}(w_3)$ acts on $(1,2,2)$ in the following way:

$$F_{FVB}(w_3)(1,2,2) = \left(-5, \frac{4}{11}, -\frac{11}{5} \right) \neq (1,2,2).$$

Therefore, the homomorphism F_{FVB} distinguishes w_3 from a trivial braid.